

Corrigenda to “Multiple Time Scale Dynamics”

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Abstract

This document is going to collect corrigenda to the book [4]. In particular, typographical and similar more minor errors will be marked in **blue** while (hopefully not many) mathematical errors will be labeled **red**. Unfortunately, the existence problem for errors is not very pleasant, e.g., suppose each page is correct with 99% probability and we take a rough page count at 800 pages total then $\mathbb{P}(\text{“no errors at all”}) = (0.99)^{800} \approx 3 \cdot 10^{-4}$ or otherwise said: the probability of no errors in the entire book would be approximately 0.03%. Hence, the existence of this document is unfortunately necessary. Please send me any errors or typos you find and I am going to include them here; please make sure you know precisely how a *correct* version should read to avoid false alarms.

p.45-46,Thm. 2.3.12: The statement (g) in the theorem is apparently not correct as stated since the foliation $\mathcal{F}^u(p)$ (and similar $\mathcal{F}^s(p)$) is only $C^{1,\alpha}$, for under the current assumptions; cf. also the (apparently equally imprecise) statement in [5] to the original hypotheses in [1, 2]. This smoothness issue does not occur for fast-slow systems, so the results in later chapters still hold.

p.55,l.13: Replace $\sup_{w \in w}$ by $\sup_{w \in W}$

p.63,l.16: Replace \mathbb{R}^2 by $\mathbb{R} \times \mathbb{R}^2$

p.63,l.-8: Replace \mathbb{R}^2 by $\mathbb{R}^2 \times \mathbb{R}$

p.93,(5.9): After the first equality, a minus sign is missing so replace “ $= (1+\delta(\dots))$ ” by “ $= -(1+\delta(\dots))$ ”

p.93,(5.10): After the equation replace “with different powers” by “with the same powers”

p.94,l.5: Replace “Example 5.7” by “equation (5.7)”

p.95,(5.17): In the line before (5.17) replace “power series” by “power”

p.100,l.-4: Replace “the inequality (5.3.3)” by the “the last inequality”

p.122,l16: Replace “sufficiently large” by “sufficiently small”

p.122,(6.17): Replace in the vector field in the second equation by $\frac{1}{5}(\dots)$, i.e., the pre-factor 1/5 is missing in front of the second equation.

p.123: In the middle of the page replace “ $0 < y^* < c_a(x_{1,-})$ ” by “ $0 < y^* < c_a(x_{1,+})$ ”

p.125,l-1: Technically speaking we have to intersect in the definition of S_0 with a compact subset, e.g., a big ball such as \mathfrak{B} defined on the next page to make S_0 compact.

p.129,l-9: Replace “ $y_i > 1$ ” by “ $i > 1$ ”

p.132: In the fourth equation it should read: $R_{11} = dy_1 \wedge (\nabla g_2 \cdot dz)$ and $R_{12} = (\nabla g_1 \cdot dz) \wedge dy_2$

p.133: In the fifth equation it should be “ $\eta_2 = E(X, t) + H(Z, X, t)$ ”

p.134: The last row in (6.31) in the last matrix should read

$$\varepsilon [-g_{2a}Z_1 - g_{2b}X_2 + g_{2y_2}X_4 + g_{1a}Z_2 + g_{1b}X_3 + g_{1y_1}X_4]$$

- p.165: In the commutative diagram in Proposition 7.1.9 and in the sentence below it, replace “ $\phi^{-1} \circ T_1$ ” by “ $\phi \circ T_1$ ”.
- p.167: In Theorem 7.1.13, or right before the statement, it might be very help to define “partially hyperbolic” as those hyperbolic objects/points having at least one hyperbolic direction.
- p.168,l-4: Replace “are directions” by “are two coordinate directions”
- p.168,l-3: Replace “ μ_i ” by “ μ_1 ”
- p.179,(R3): Important typo: replace $c_2 \ln \varepsilon$ by $c_2 \varepsilon \ln \varepsilon$
- p.214,(8.41): In the middle column replace y_1 and y_2 by \dot{y}_1 and \dot{y}_2
- p.229,(8.67): The first equality should be an inequality $\frac{\partial^2 f}{\partial x^2}(0, 0, 0) \neq 0$. Furthermore, in the matrix inside the determinant the lower right entry is a double derivative with respect to y , not x .
- p.362-363: The implicit assumption “ $g(0, 0, y, 0) > 0$ for all $y \in \mathbb{R}$ ” (or in a suitable compact set on which the slow flow is considered) should have been stated explicitly. Add this as assumption (A5) on p.362 and then replace (A1)-(A4) by (A1)-(A5) in Theorem 12.2.3 on p.363.
- p.364,l-3: Replace “ $\gamma(\tau_a)$ is $\mathcal{O}(1)$ ” by “ $\gamma(\tau_b)$ is $\mathcal{O}(1)$ ”.
- p.366,l.2: Replace “solutions remains” by “solution generically remains”; generic breaking of the slow manifold is again required, similar to the discussion in the remark on p.363, to actually get departure at the buffer point.
- p.400, Fig. 13.2: Swap the labels y_1 and y_2 in part (a) of the figure.
- p.414,(13.20): Although it is clear from this equation that there are two objects V_1 and V_1 , it might be better to change the subscripts so that no confusion can arise here and in related passages of Section 13.6.
- p.603,(18.44): Replace “ $-\tau D_2 f(\xi, \xi)+$ ” by “ $-\tau D_2 f(\xi, \xi) f(\xi, \xi)+$ ”.
- p.604,l.6: Replace “ $\tilde{F}_\tau(\xi, \tau)$ ” by “ $\tilde{F}_\tau(\xi, 0)$ ”.
- p.757: The reference [Kue10a] in the book has the title (“Characterizing slow exit points”) of an earlier arXiv version of the paper. It should be correctly cited as appearing in the reference [3] below.
- p.807: The two entries for “Liénard transformation” should be grouped into one entry reading “Liénard transformation, 9, 573”.

References

- [1] N. Fenichel. Asymptotic stability with rate conditions. *Indiana U. Math. J.*, 23:1109–1137, 1974.
- [2] N. Fenichel. Asymptotic stability with rate conditions II. *Indiana U. Math. J.*, 26:81–93, 1977.
- [3] C. Kuehn. Connecting fast-slow systems and Conley index theory via transversality. *Electron. J. Differential Equations*, 2010(106):1–20, 2010.
- [4] C. Kuehn. *Multiple Time Scale Dynamics*. Springer, 2015.
- [5] S. Wiggins. *Normally Hyperbolic Invariant Manifolds in Dynamical Systems*. Springer, 1994.